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Also available as a kit at

# 7 Segment Basic Version

Reactive Lilght with 7 Segment Display



### Grundversion Reactive Light with 7 Segment Display

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## Teil I. The circuit

#### 1. Functional description

This circuit is the basic version of the reactive lights. It is easy to make with just a few elements and usable without parameterization. Instead of a simple LED a 7 segment LED display is used to show sequences of numbers and decimal points.

The measurement of brightness is done by a photo resistor (LDR). During daylight the circuit goes into a standby mode and is inactive. It just measures periodically the brightness to detect the beginning of the night and set the circuit into an active mode. If in this mode the LDR is lit, the circuit will return the programmed sequence using the 7 segment LED display and wait for the next activation.

Because of the very small power consumption the circuit can be run for years with just a set of batteries.

#### 2. Circuit diagram

Figure 1 shows the circuit diagram of the reactive light.

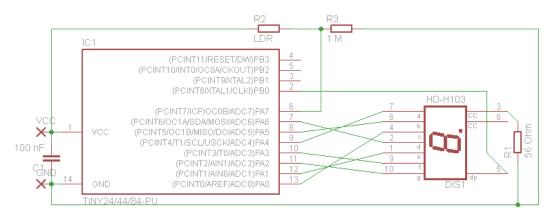


Abbildung 1: Circuit diagram.

On the left one can find the microcontroller, left of it the power supply. The circuit needs a voltage of 3 V. Two standard batteries in sequence make this voltage. The plus terminal must be connected to pin +, the minus terminal to the pin –. Above the IC is the measurement of the brightness, consisting of R3 and the photo resistor R2. On the right the 7 segment LED display (common cathode) with its resistor can be found. Because of the program structure just one resistor is needed for all eight LEDs of the display.

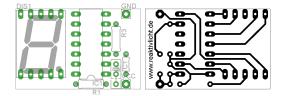


Abbildung 2: Layout of the circuit board.

A draft of the circuit board is shown in figure 2. The left figure shows the component side, the right one the circuit paths seen from the lower side. When mounting one has

to care about the polarity of the IC (the denting has to point to the capacitor).

#### 3. Programmierung

```
1 $regfile = "ATtiny84.DAT"
2 $crystal = 16000
3  $hwstack = 3
4
5 Config Adc = Single , Prescaler = Auto
6 Ddra = &B01111111
7 Porta = &B0000000
8 Ddrb = &B0000001
9 Portb = &B0000000
10
11 Stop Ac
12
13 Wdtcr = \&B11010000
14 Enable Interrupts
15
16 Const Threshold = 15
17 Const Daylight = 950
18 Const Maxdigits = 512
19
20 Dim Ldr As Integer
21 Dim Oldldr As Integer
22 Dim Deltaldr As Integer
23
24 Dim Daylightcounter As Integer
25
26 Dim E As Byte
27 Dim J As Integer
28 Dim X As Integer
29
30 Do
31
     Start Adc
32
     Ldr = Getadc(7)
33
     Stop Adc
34
     Deltaldr = Ldr - Oldldr
35
     Oldldr = Ldr
36
37
     If Deltaldr > Threshold Then
38
      Gosub Show
39
```

```
01d1dr = 1024
40
41
     End If
42
     If Ldr > Daylight Then
43
44
       If Daylightcounter < 255 Then
         Daylightcounter = Daylightcounter + 1
45
       End If
46
     Else
47
       Daylightcounter = 0
48
49
     End If
     If Daylightcounter > 200 Then
50
       Gosub Pause_8
51
     End If
52
53
     Gosub Pause_0125
54
55
56
  Loop
57
  Show:
58
      X = 0
59
      E = 0
60
      While E < 11 And X < Maxdigits
61
62
        Readeeprom E , X
        If E < 11 Then
63
          For J = 0 To 100
64
65
             Gosub Show_dig
           Next J
66
           Gosub Pause_0125
67
        End If
68
        X = X + 1
69
      Wend
70
71 Return
72
73 Pause_0125:
     Wdtcr = \&B11010011
74
     Reset Watchdog
75
     Powerdown
76
  Return
77
78
79 Pause_8:
     Wdtcr = &B11110001
80
81
     Reset Watchdog
     Powerdown
82
83 Return
```

```
84
   Show_dig:
85
      If E = 0 Then
86
        Gosub Dig_0
87
88
      Elseif E = 1 Then
89
        Gosub Dig_1
      Elseif E = 2 Then
90
        Gosub Dig_2
91
      Elseif E = 3 Then
92
93
        Gosub Dig_3
94
      Elseif E = 4 Then
        Gosub Dig_4
95
      Elseif E = 5 Then
96
        Gosub Dig_5
97
      Elseif E = 6 Then
98
        Gosub Dig_6
99
      Elseif E = 7 Then
100
101
        Gosub Dig_7
      Elseif E = 8 Then
102
        Gosub Dig_8
103
      Elseif E = 9 Then
104
        Gosub Dig_9
105
106
      Elseif E = 10 Then
        Gosub Dig_dot
107
      End If
108
109
   Return
110
111 Dig_dot:
112
      Portb.0 = 1
113
      Waitms 5
      Portb.0 = 0
114
      Waitms 5
115
     Waitms 5
116
117
      Waitms 5
118
      Waitms 5
      Waitms 5
119
      Waitms 5
120
121 Return
122
123 Dig_0:
      Porta.5 = 1
124
      Waitms 5
125
      Porta.5 = 0
126
      Porta.0 = 1
127
```

```
Waitms 5
128
129
      Porta.0 = 0
      Porta.6 = 1
130
      Waitms 5
131
132
      Porta.6 = 0
      Porta.1 = 1
133
      Waitms 5
134
      Porta.1 = 0
135
     Porta.3 = 1
136
137
      Waitms 5
      Porta.3 = 0
138
      Porta.4 = 1
139
      Waitms 5
140
      Porta.4 = 0
141
142
      Waitms 5
143 Return
144
145 Dig_1:
     Waitms 5
146
      Porta.5 = 1
147
      Waitms 5
148
      Porta.5 = 0
149
150
     Porta.0 = 1
     Waitms 5
151
      Porta.0 = 0
152
153
      Waitms 5
      Waitms 5
154
      Waitms 5
155
      Waitms 5
156
157 Return
158
159 Dig_2:
     Porta.4 = 1
160
161
      Waitms 5
      Porta.4 = 0
162
      Porta.5 = 1
163
      Waitms 5
164
      Porta.5 = 0
165
      Waitms 5
166
167
      Porta.6 = 1
      Waitms 5
168
      Porta.6 = 0
169
      Porta.1 = 1
170
      Waitms 5
171
```

```
172
      Porta.1 = 0
173
      Waitms 5
      Porta.2 = 1
174
      Waitms 5
175
      Porta.2 = 0
176
177 Return
178
179 Dig_3:
     Porta.4 = 1
180
181
      Waitms 5
      Porta.4 = 0
182
      Porta.5 = 1
183
      Waitms 5
184
      Porta.5 = 0
185
186
      Porta.0 = 1
187
      Waitms 5
      Porta.0 = 0
188
      Porta.6 = 1
189
      Waitms 5
190
      Porta.6 = 0
191
      Waitms 5
192
      Waitms 5
193
194
      Porta.2 = 1
      Waitms 5
195
      Porta.2 = 0
196
197 Return
198
199 Dig_4:
      Waitms 5
200
      Porta.5 = 1
201
      Waitms 5
202
      Porta.5 = 0
203
     Porta.0 = 1
204
205
      Waitms 5
      Porta.0 = 0
206
      Waitms 5
207
      Waitms 5
208
      Porta.3 = 1
209
      Waitms 5
210
211
      Porta.3 = 0
      Porta.2 = 1
212
      Waitms 5
213
214
      Porta.2 = 0
215 Return
```

```
216
217 Dig_5:
218
      Porta.4 = 1
      Waitms 5
219
220
      Porta.4 = 0
      Waitms 5
221
      Porta.0 = 1
222
      Waitms 5
223
      Porta.0 = 0
224
225
      Porta.6 = 1
226
      Waitms 5
      Porta.6 = 0
227
      Waitms 5
228
      Porta.3 = 1
229
230
      Waitms 5
231
      Porta.3 = 0
      Porta.2 = 1
232
      Waitms 5
233
      Porta.2 = 0
234
235 Return
236
237 Dig_6:
238
      Porta.4 = 1
      Waitms 5
239
      Porta.4 = 0
240
      Porta.3 = 1
241
      Waitms 5
242
243
     Porta.3 = 0
      Porta.0 = 1
244
      Waitms 5
245
      Porta.0 = 0
246
      Porta.6 = 1
247
      Waitms 5
248
249
      Porta.6 = 0
      Porta.1 = 1
250
      Waitms 5
251
      Porta.1 = 0
252
      Waitms 5
253
      Porta.2 = 1
254
255
      Waitms 5
      Porta.2 = 0
256
257 Return
258
259 Dig_7:
```

```
260
      Porta.4 = 1
261
      Waitms 5
      Porta.4 = 0
262
      Porta.5 = 1
263
264
      Waitms 5
      Porta.5 = 0
265
      Porta.0 = 1
266
      Waitms 5
267
      Porta.0 = 0
268
269
      Waitms 5
270
      Waitms 5
      Waitms 5
271
      Waitms 5
272
273 Return
274
275 Dig_8:
      Porta.5 = 1
276
      Waitms 5
277
      Porta.5 = 0
278
      Porta.0 = 1
279
      Waitms 5
280
      Porta.0 = 0
281
282
      Porta.6 = 1
      Waitms 5
283
      Porta.6 = 0
284
      Porta.1 = 1
285
      Waitms 5
286
287
      Porta.1 = 0
      Porta.3 = 1
288
      Waitms 5
289
      Porta.3 = 0
290
      Porta.4 = 1
291
      Waitms 5
292
      Porta.4 = 0
293
      Porta.2 = 1
294
      Waitms 5
295
      Porta.2 = 0
296
   Return
297
298
299 Dig_9:
      Porta.4 = 1
300
      Waitms 5
301
302
      Porta.4 = 0
      Porta.5 = 1
303
```

304	Waitms 5
305	Porta.5 = 0
306	Porta.0 = 1
307	Waitms 5
308	Porta.0 = 0
309	Porta.6 = 1
310	Waitms 5
311	Porta.6 = 0
312	Waitms 5
313	Porta.3 = 1
314	Waitms 5
315	Porta.3 = 0
316	Porta.2 = 1
317	Waitms 5
318	Porta.2 = 0
319	Return
320	
321	End

In line 1 to 3 general settings are done. First the type of the processor is told to the compiler. Afterwards the frequency of the intern oscillator is set. At last the stack is set to 3 so that there is enough space for the variables of the program. The consequence is that the nesting depth of function calls can be maximum three, which is enough for this program.

Then the microcontroller is configured by the registers. First the analog digital converter that is used to measure the brightness is configured. Afterwards pins 0 - 6 of port A and pin 0 of Port B are configured as outputs and set to low. They are used for controlling the LED display. The other ports are inputs. In line 11 the analog comparator is switched off to reduce the power consumption. It is not used in this program. Line 13 and 14 configure the watchdog timer that is used for realizing the delays to 0.125 s and interrupt mode.

Now the contants and variables of the program are defined. Treshold is the minimum change of the brightness between two cycles that triggers the reactive light. By changing this value the sensitivity can be adjusted. If the brightness is above Daylight, the controller will go to standby mode. Maxdigits has to be set to the number of bytes of the EEPROM. This value depends on the used controller. The ATtiny22A has 128 Byte, the ATtiny44A 256 Byte and the ATtiny84A 512 Byte. The current brightness is stored in Ldr, the one of the previous cycle in Oldldr. Deltaldr is a variable that is used for storing the difference between these two values. In Daylightcounter the cycles with a brightness bigger than Daylight are counted. E contains the code of the digit to be shown. J is a counter. X is the adress of the EEPROM memory cell to be read.

The lines 30 to 56 contain the main program. At the beginning the analog digital converter is started in lines 32 to 41, the value of brightness read and the converter switched off again. The difference to the previous cycle is calculated and the actual

brightness stored at the variable Oldldr for the next cycle. If the difference is bigger than the treshold, the routine Show is called. Afterwards Oldldr is set to maximum value to prevent the program being triggered twice. That is possible when the brightness increases during showing the sequence. As of line 33 the conditions for the standby mode are checked. If the brightness is bigger that the daylight treshold, the daylight counter is incremented. Otherwise it is set to 0. If the daylight counter reaches the value 200, which means that during 200 cycles at 0.125 s daylight was detected, the procedure Pause\_8 is called. At last the controller is set to standby for 0.125 s. That's the interval for calculating the difference of the brightness between two cycles.

The procedure Show is in the lines 58 to 71. All bytes of the EEPROM are read until one byte is bigger than 10 or the end of the EEPROM is reached. For each value the procedure Show\_dig is called 100 times. The time each digit is shown can be adjusted by the number of calls.

The lines 73 to 83 contain procedures to set the controller for 125 ms or 8 s to standby. At the beginning the watchdog timer is set to the specified time. After that the controller is set to standby. After the time is elapsed, the program is continued.

The procedure Show\_dig in lines 85 to 109 calls depending on the variable E other procedures that show the corresponding digit at the display. These procedures are located in lines 111 to 319. Each procedure consists of an identical number of delay steps to make each digit the same length and brightness. One after the other the needed segments are lightened for one delay step. As always just one segment is lightened, a common resistor for all segments can be used.

The sequence to be shown has to be stored in the EEPROM. The values 0x00 - 0x09 represent the digits 0 - 9. The decimal point is coded as 0x0A. Values from 0x0B to 0xFF indicate the end of the sequence.

## Teil II. Known problems

#### 4. Two segments of the display do not work.

During soldering probably a short-circuit between the pins of these two segments arose. It must be removed.

## 5. The device does not work and the microcontroller becomes very hot.

Either the microcontroller is placed incorrect of the power supply is reverse poled.